

# Magnetic field measurements of superconducting dipole magnets for the SIS100 Synchrotron

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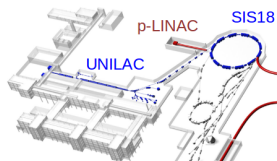
IMMW21, Grenoble 2019, June 24 - 28

**Preliminary draft**

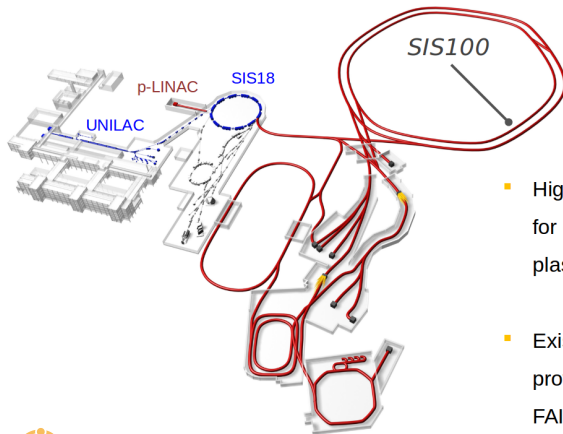
# The FAIR project

**FAIR** = **F**acility for **A**ntiproton an **I**on **R**esearch

*Existing GSI facility*



*FAIR facility*



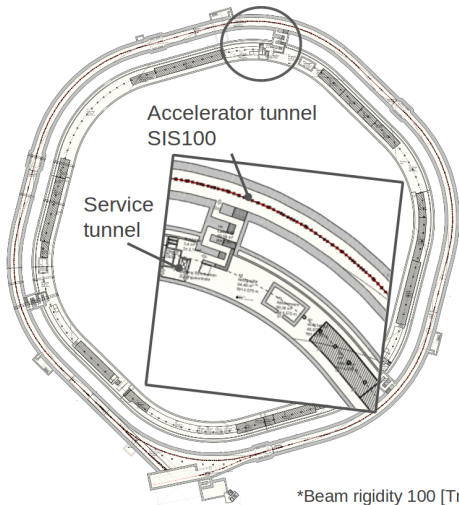
*International project*



- High intensity ion and antiproton beams for experiments in nuclear, atomic, plasma physics and material science.
- Existing facility UNILAC/SIS18 will provide ion-beam source and injector for FAIR.

# Heavy Ion Synchrotron SIS100

SIS100 = **S**chwer**i**onen**s**ynchrotron 100 [Tm] = Heavy ion synchrotron (beam rigidity 100 [Tm]\*)



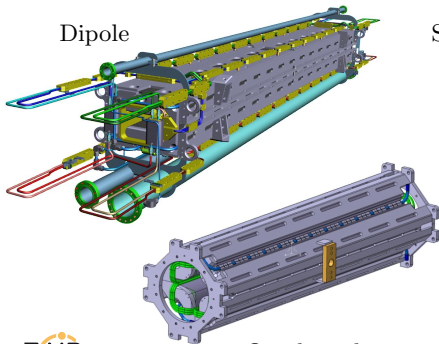
- Hexagonal, circumference 1083.60 m
- Operational modes:
  - Ultra High Vacuum ( $10^{-11}$  mbar)
    - Adsorption by cold vacuum chamber (10 - 15K)
    - Superconducting (magnet) accelerator
  - Fast-ramp machine  $\sim 0.5$  sec. to maximum field

\*Beam rigidity 100 [Tm] = Bending dipole field 1.9 [T]  $\times$  Bending radius 52.632 [m]

# Magnets for SIS100

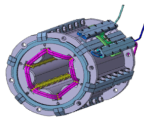
	unit	Main Dipole	Main Quadrupole	Multipole corrector (nested)			Steerer (nested)	Chromaticity sextupole
				Quadrupole	Skew sextupole	Octupole	Horizontal/Vertical	Sextupole
Number of Magnets		108	166	12	12	12	83	48
Magnetic field strength	T/m <sup>n-1</sup>	1.9	27.7	0.75	25	333.3	0.3	175
Effective length	m	3.062	1.3	0.75			0.5	0.5
Usable aperture	mm			150			135/65	135/65
Ramp time to Max.	Sec.	0.5		0.15	0.24	0.24	0.2	0.175

Dipole

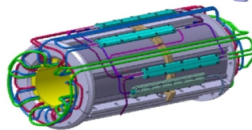
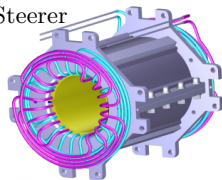


Quadrupole

Sextupole



Steerer



Multipolcorrector



# The SIS100 Dipole Magnet design parameters

Specifications and beam dynamic requirements:

- Iron dominated superconducting (superferric) magnets

- Forced flow two phase helium cooling (4.5 K)

- Maximum magnetic induction

$$B_{max} = 1.9 \text{ T}$$

- Maximum ramp rate

$$dB/dt = 4 \text{ T/s}$$

- Field homogeneity requirement

$$\Delta B/B = \pm 6 \times 10^{-4}$$

- Yoke gap height variations

$$\Delta h = \pm 0.1 \text{ mm}$$

- Yoke length

$$L_Y = (3.002 \pm 0.0004) \text{ m}$$

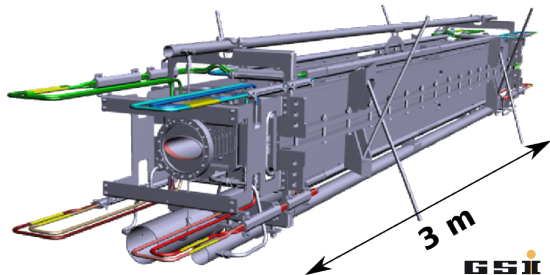
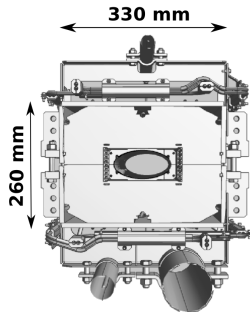
- Effective magnetic length

$$L_{\text{Eff}} = 3.062 \text{ m}$$

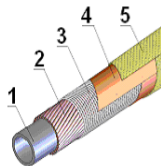
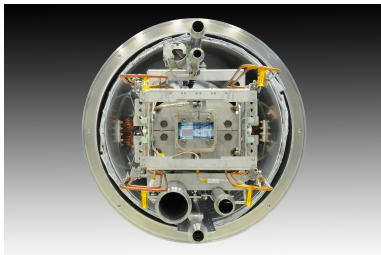
- Total length (coils)  $L_{\text{Tot}} = 3.2 \text{ m}$

- Bending angle  $3\frac{1}{3}^\circ$

- Radius of curvature 52.632 m

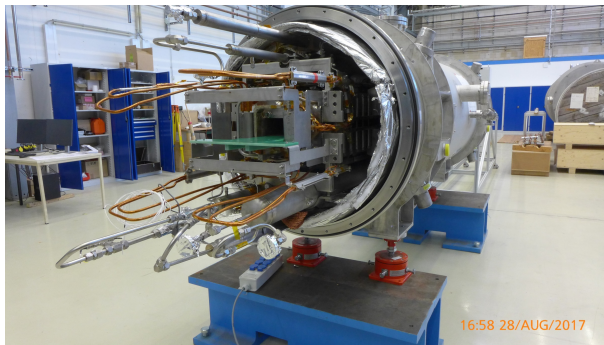


# SIS100 Dipole Magnet



## Nuclotron cable:

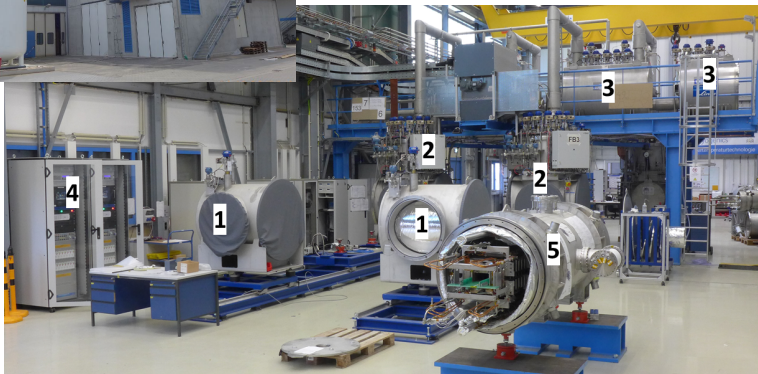
- 1 - Cooling tube CuNi
- 2 - SC wire NbTi
- 3 - CrNi wire
- 4 - Kapton tape
- 5 - Glasfiber tape



# Serial Test Facility

Cryo- and power-supply

- 1 Endbox
- 2 Feedboxes
- 3 Cryo-plant - cooling power of 1.5 kW equivalent
- 4 Quench detection
- 5 Dipole magnet



# Testing overview

- Yoke geometrie:
  - Aperture height
  - Sag and twist
  - Position
- Process lines
  - Pressure and leaks
  - massflow rate
  - positioning
- Electrical tests
  - High Voltage
  - Continuity (voltage tabs for quench detection)
  - Turn-to-turn Insulation
- Quench detection
- Static heat load and AC-losses
- Magnetic field
  - Integral B-field
  - Harmonics
  - Load line (transfer function)
- For all dipole magnets (110 in total):
  - about 30 parameters to control
  - about 100 steps to follow
  - duration  $\sim 3$  weeks

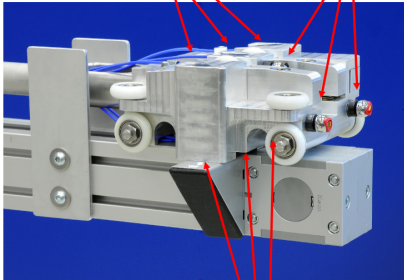
# Aperture height measurement system

## Aperture Height Measurement of SIS 100 Dipoles

Sensorcarrier with capacitive Sensors und Lasertracker SMR's

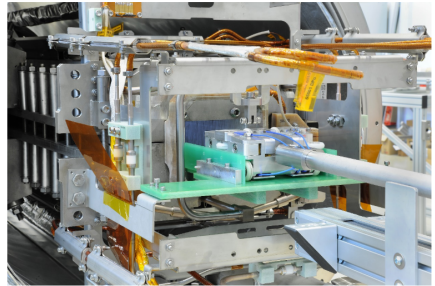
3x upper Sensors

3x Lasertracker  
SMR's



Measurement unit

3x lower Sensors



Measurement unit insertion

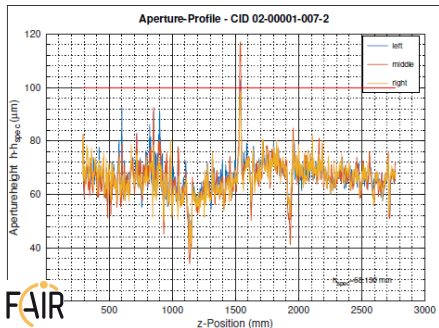
# Aperture height measurement results

**Height:**

Specification:  $h_{\text{spec}} = 68.130_{-0.0}^{+0.1}$  mm

Measurement errors:

- repeatability:  $\pm 3\mu\text{m}$
- absolute:  $\pm 15\mu\text{m}$

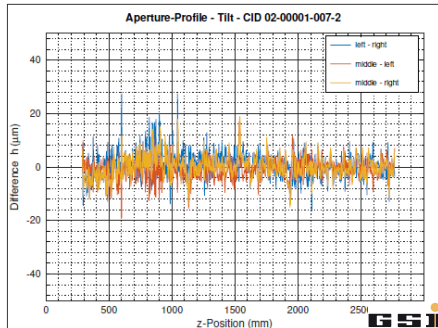


**Tilt:** no specifications

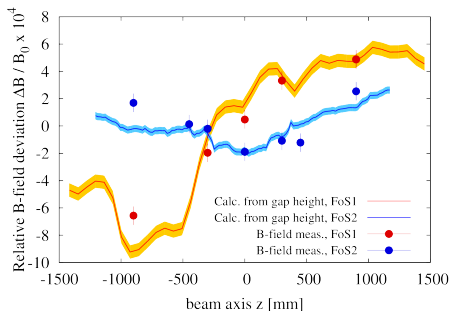
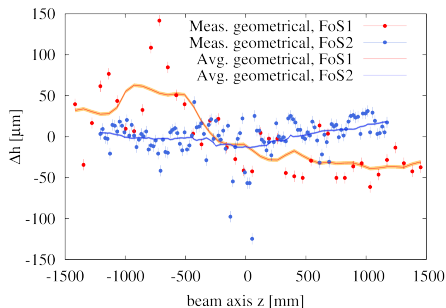
If there is something conspicuous it would be a warning.

Maybe there would be correlations with higher harmonics in the magnetic field.

But: no indications up to now !



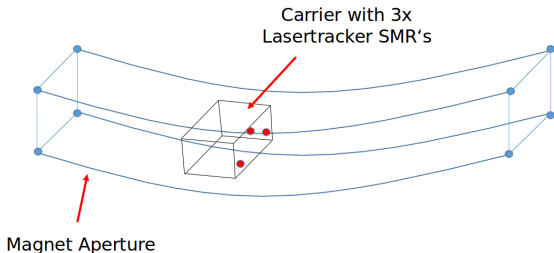
# Dipole



- Magnetic field measured at different positions along the beam axis with rotating coils
- Relative gap height deviations measured with high resolution along the beam axis with capacitive sensors.
- Gap data averaged with respect to rotating coil length of 600 mm.
- Conversion of gap height to field strength using  $B = \frac{IN\mu_0}{h}$  (and arbitrary offset correction)
- ▷ Comparison with  $B$  field measurements in good agreement

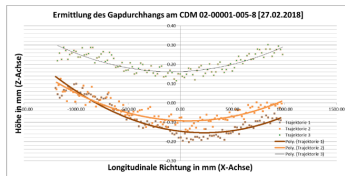
## Additional assets

Additional outcome with Lasertracker



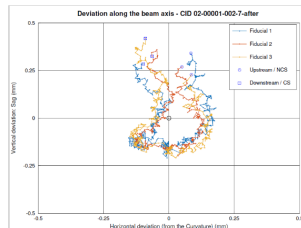
Trajectory can be tracked during Aperture Height Measurement

## Sag of Yoke



Durchgang	Trajektorie 1	Trajektorie 2	Trajektorie 3	Mittelwert
	0.30	0.27	0.21	0.26

## Torsion of Yoke





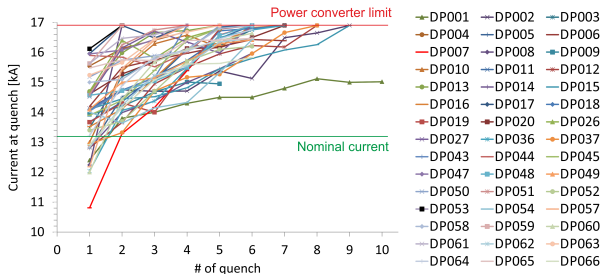
# Quench training

## Specifications:

- nominal current of 13.2 kA has to be reached
  - before 3<sup>rd</sup> quench in the first cycle
  - before 1<sup>st</sup> quench from now on
- de-training limited to 5% (compared to previous quench)
- quench current has to stabilize at > 110% at least (14.5 kA).

## Results:

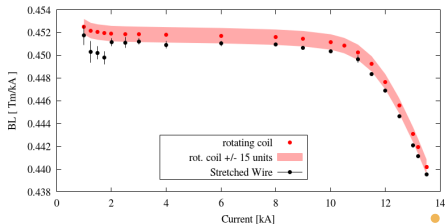
- nominal current reached at 2nd quench at least
- no significant de-training observed
- Excellent quench performance!
- Limit of cable (17.8 kA) nearly reached
- high stability of coil structure in the yoke



# Calibrations

- Measure segment by segment at 300K in a normal conducting magnet
  - Magnetic field is known from hall probe and NMR mapping.
- absolute field strength calibration
- calibrate gaps in between the coils (needed for magnetic length)
- Compare tilt angles from segment to segment
- apply correction for cold measurements (with small constraints).

- Additional measurement with a stretched wire
    - different lab at GSI
    - different power converter
- independent determination of the magnetic length
- confirmation of systematic error estimation of rotating coil results of  $\pm 15$  units

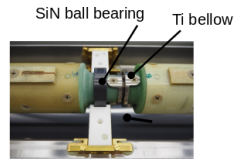
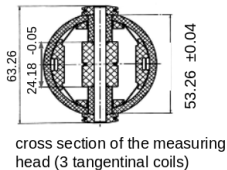
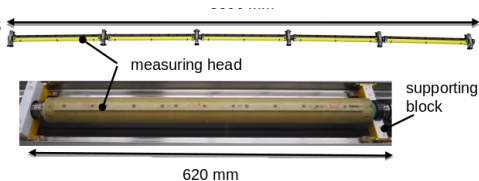




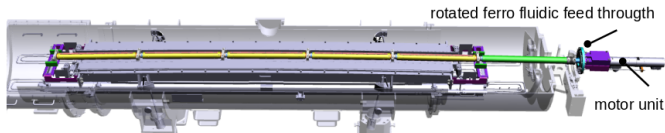
# Rotating coils

## System for magnetic field measurements

- ✓ 5 measuring heads – tangential coils
- ✓ 3 pick up coils per head, 600 mm length
- ✓ effective surface 1.67 m<sup>2</sup>
- ✓ Ti-alloy bellows – interconnection between segments and to align the heads along the beam axis
- ✓ SiN ball bearings for rotation motion
- ✓ ceramic supporting blocks for transverse positioning in the gap



Field measurements  
in vacuum @ 4.5K

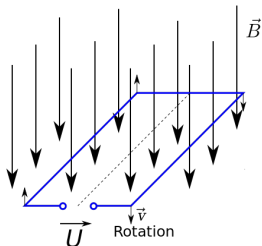


The measuring probe is designed and built in collaboration with CERN

# Magnetic flux and induction

Magnetic flux:

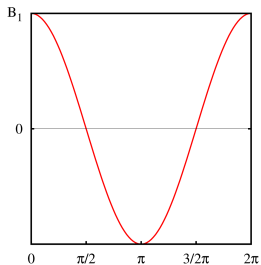
$$\Phi = \int \vec{B} dA$$



Faraday's law:

$$U_{\text{Ind}} = -\frac{d\Phi}{dt}$$

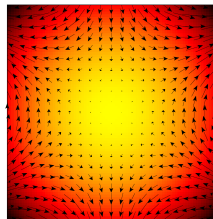
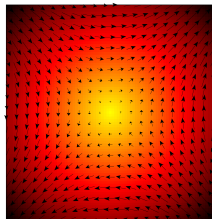
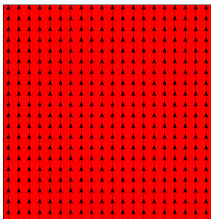
To measure  $U_{\text{Ind}}$  we have to change either  $B$  or  $A$  (or both)



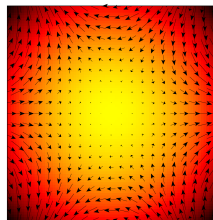
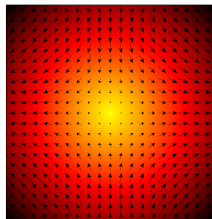
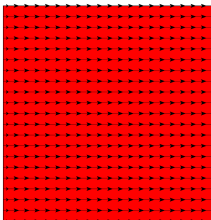
Signal from constant dipole  
and rotating coil

# Multipole expansion

normal  
 $B_n$



skew  
 $A_n$

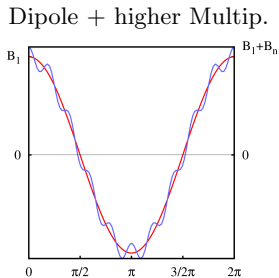
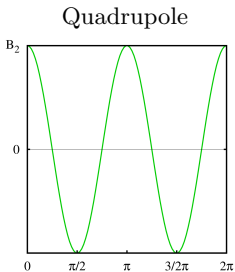
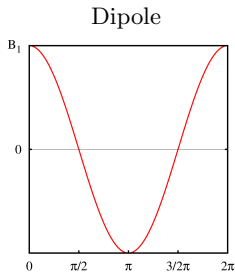


Dipole

Quadrupole

Sextupole

# Multipole expansion

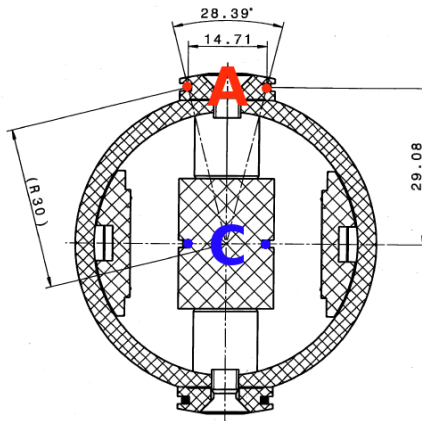


Fourier Transformation of measured signal leads to multipole coefficients of magnetic field:

$$\mathbf{C}_n = \text{FT}(\text{Signal}) / \mathbf{K}_n, \quad (\mathbf{K}_n: \text{geometrical sensitivity})$$

$$\mathbf{B}(\mathbf{z}) = \sum_{n=1}^{\infty} \mathbf{C}_n \left( \frac{\mathbf{z}}{R_{\text{ref}}} \right)^{n-1}, \quad \mathbf{C}_n = B_n + iA_n$$

# Compensation method



## Sensitivity:

for dipole field:

$$\mathbf{K}_1(\text{CoilA}) = \mathbf{K}_1(\text{CoilC})$$

for higher Multipoles:

$$\mathbf{K}_{n>1}(\text{CoilC}) = 0$$

## Compensation method:

subtract Signal(C) from Signal(A)

→ discrimination of dipole and noise

→ precise higher harmonics spectrum

→ use signal A for dipole measurement

→ use signal A-C for higher harmonics

precision $\sim 10^{-5}$
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# Magnetic length, Transferfunction

## Acceptance criterium for SIS100

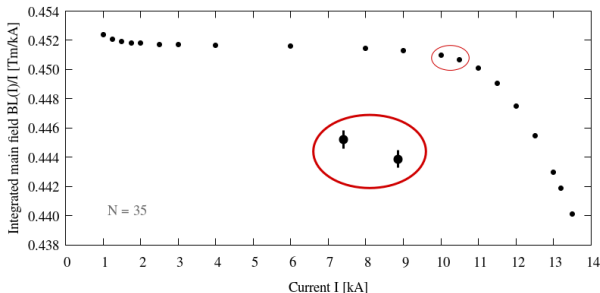
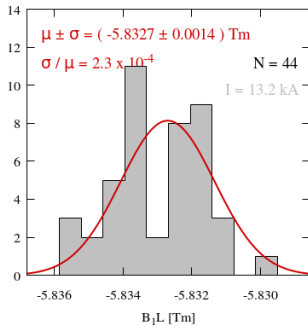
(with intergral field  $BL = \int B(l) dl$ ):

$$\frac{\Delta BL}{BL} \leq 4 \times 10^{-3}$$

Measured 44 Magnets:

$$\frac{\Delta BL}{BL} \leq 2.3 \times 10^{-4}$$

(factor 10 better than requested!)



# Systematics from different Shafts and FeedBoxes

The same magnet was measured

- at 3 different feedboxes
- with 2 different shafts

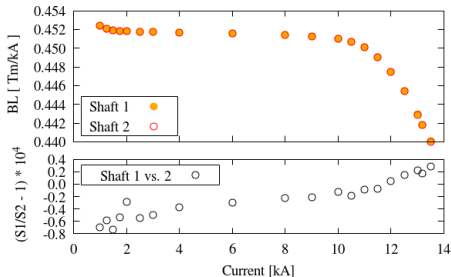
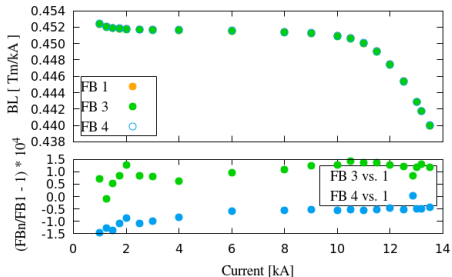
This includes systematics from

- power supplies
- mechanical installation
- dimensions of rotating coils

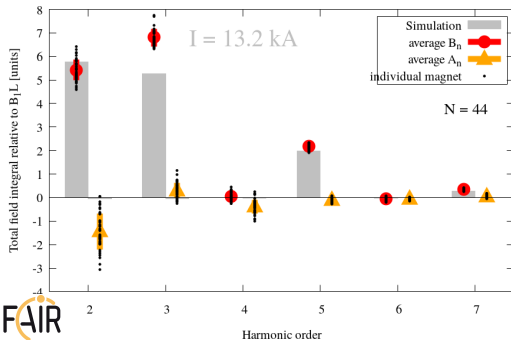
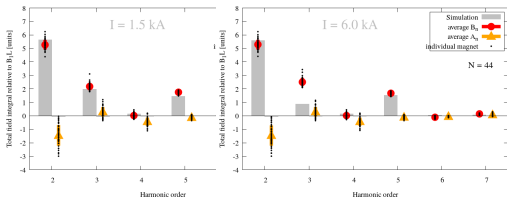
→ very good reproducibility

→ very stable system

→ relative errors in the range of units ( $10^{-4}$ ).



# Harmonics



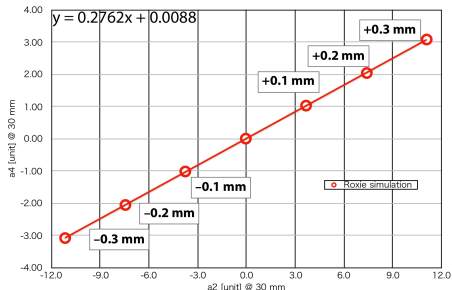
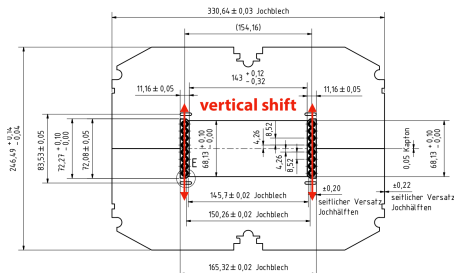
$$\mathbf{B}(\mathbf{z}) = \sum_{n=1}^{\infty} \mathbf{C}_n \left( \frac{\mathbf{z}}{R_{\text{ref}}} \right)^{n-1}$$

$$\mathbf{C}_n = B_n + iA_n, \quad \mathbf{z} = x + iy$$

- $B_2$  (normal quadrupole):  
from end field (expected from magnetic design)
- $B_3, B_5$  (normal sextu-/decapole)  
"allowed" harmonics, same symmetry as dipole, can be corrected in the ring
- all other  $B_n \approx 0$
- But not  $A_2$  (skew quadrupole)!

Where is A<sub>2</sub> coming from ?

- Displacement of rotating coil? Ruled out by simulations. No shift or tilt can create A<sub>2</sub>.
- A shift of the magnetic coil and/or an asymmetrie in the yoke would cause A<sub>2</sub>.
- Confirmation by Roxie2D simulations shows A<sub>4</sub> ~ A<sub>2</sub>

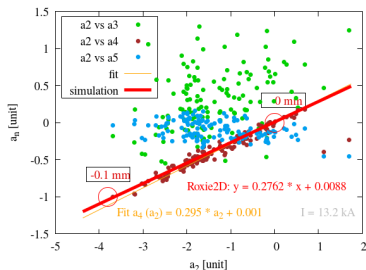
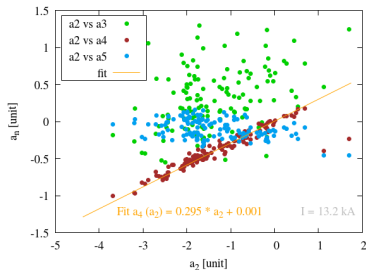


## $A_2$ discussion (part2)

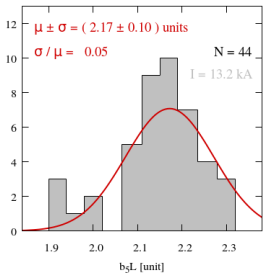
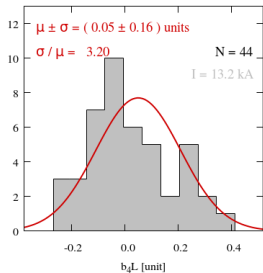
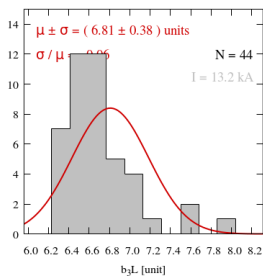
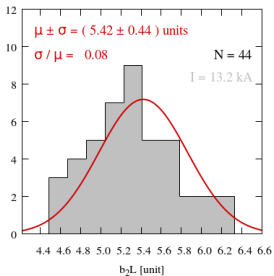
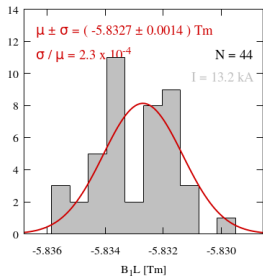
- Measurement results show a linear behaviour  $A_4 \sim A_2$ .
- Fits perfectly to Roxie2D prediction
- Coil shift / yoke asymmetrie in the order of  $\sim 50 \mu\text{m}$ .
- production steps were reviewed, but no obvious reasons were found.

Is  $A_2$  critical ?

→ No! Uncertainties in the alignment of quadrupole magnets in the ring will cause much bigger  $A_2$ .



# Statistics

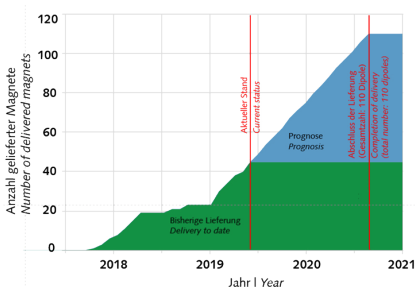


44 Magnets tested up to now

- excellent results
- stable production
- stable measurement system

# SIS100 Dipole production

- 110 dipoles in total
- 46 dipoles delivered (current rate 1 per week)
- 44 tested
- excellent magnetic field properties
- excellent yoke geometry
- excellent quench behaviour
- problems with process line positions (solved)
- problems with untight feedthroughs (under discussion)



It's on a good track!

# The last but most important slide: the team at GSI

- Survey & Alignment
- Electrical tests
- Quench detection
- Magnetic field measurements
- Software: DAQ & Analysis
- Cryo operator
- power supply maintenance
- Transport & Installation
- Quality assurance
- Communication with production

